



ORION ARTEMIS I ENTRY PERFORMANCE

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46th AAS GUIDANCE, NAVIGATION, AND CONTROL CONFERENCE

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ARTEMIS I



◆ **Launched**

- November 16, 2022 at 1:47 am

◆ **Mission Duration**

- 25 days, 10 hours, 53 minutes

◆ **Primary landing zone near San Diego**

- Skip entry allows access across lunar month
- Artemis I shifted 300 nmi south due to weather
- EI to splashdown range ~3200 nmi

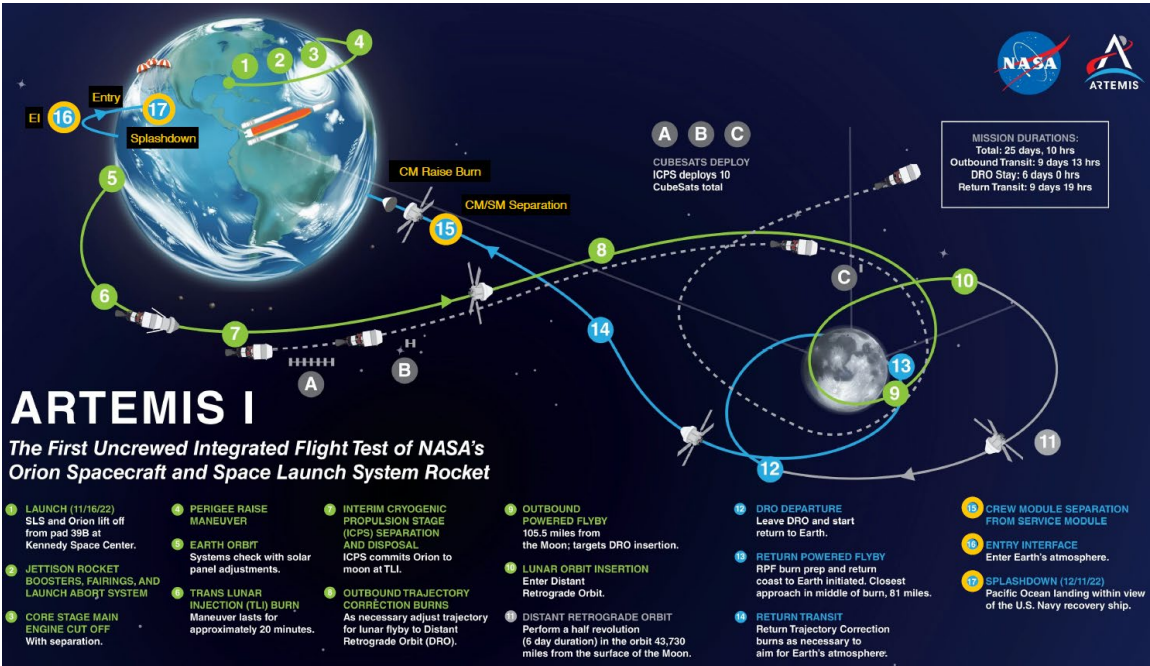
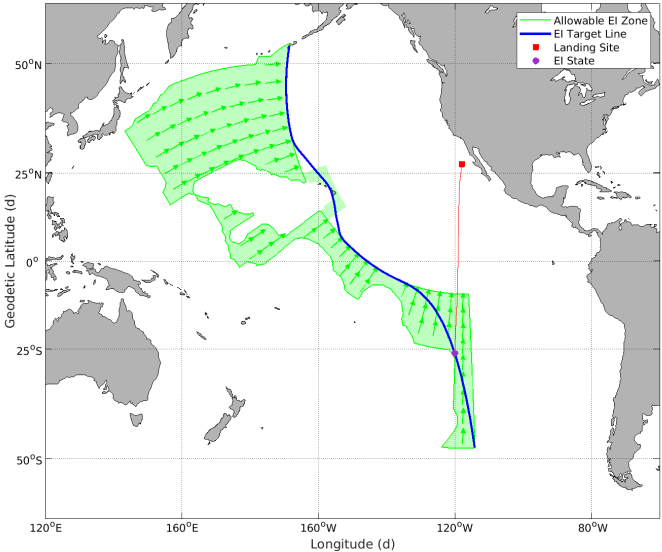
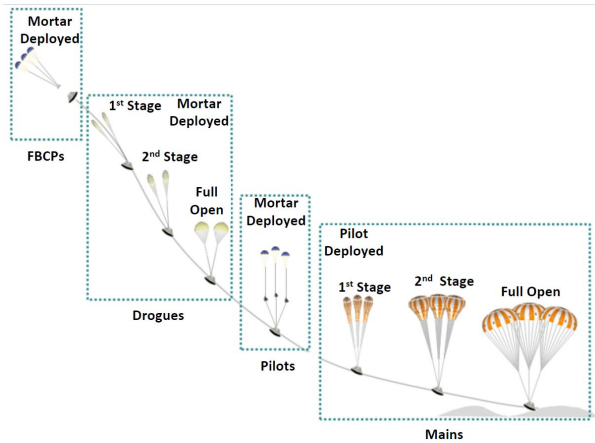


Table 1: Artemis I Entry Interface State

Parameter	Units	Artemis I
Geodetic Altitude	ft	400000.0
Geodetic Latitude	deg	-25.82847
Longitude	deg	-120.08071
Inertial Velocity Magnitude	ft/s	36062.65680
Inertial Topocentric Flight Path Angle	deg	-5.66367
Inertial Topocentric Azimuth	deg	4.65389
Total Range-to-Target	nmi	3176.65
Lateral Angle	deg	0.94018

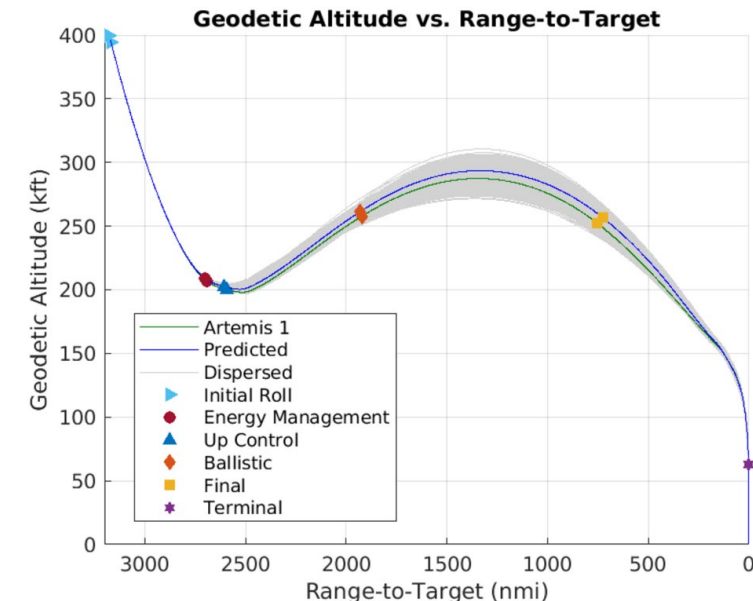
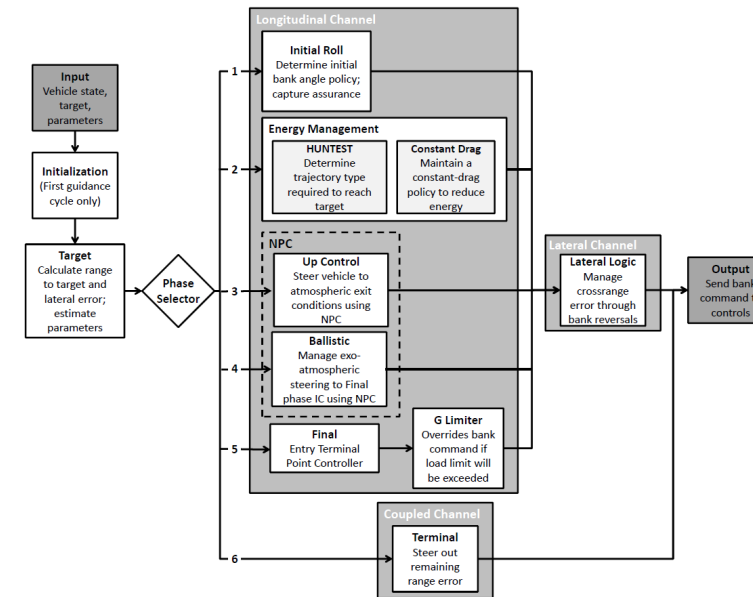




PREDGUID ENTRY GUIDANCE



- ◆ **Generates bank command to achieve target**
- ◆ **Based on Apollo entry guidance, with changes only where needed to improve performance**
 - Numerical Predictor-Corrector (NPC) for range prediction, rather than analytic methods, in early entry guidance phases
 - In-flight estimation of atmospheric density and vehicle lift-to-drag ratio (L/D)
 - Interpolation of the Final phase reference trajectory, rather than nearest-neighbor
 - Addition of Terminal phase steering
- ◆ **Decoupled downrange and crossrange channels**
- ◆ **NPC taken from Aeroassist Flight Experiment**
 - Propagates constant bank angle solution
 - Iterates on bank angle to converge on range
- ◆ **Six phases**

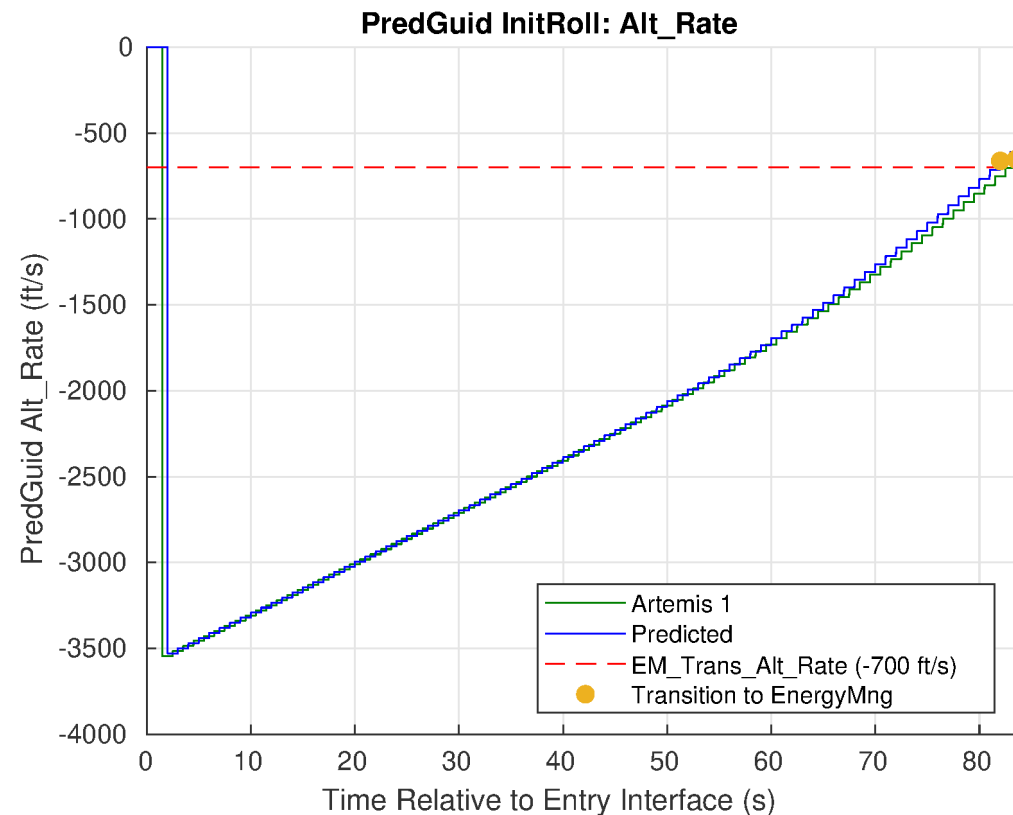
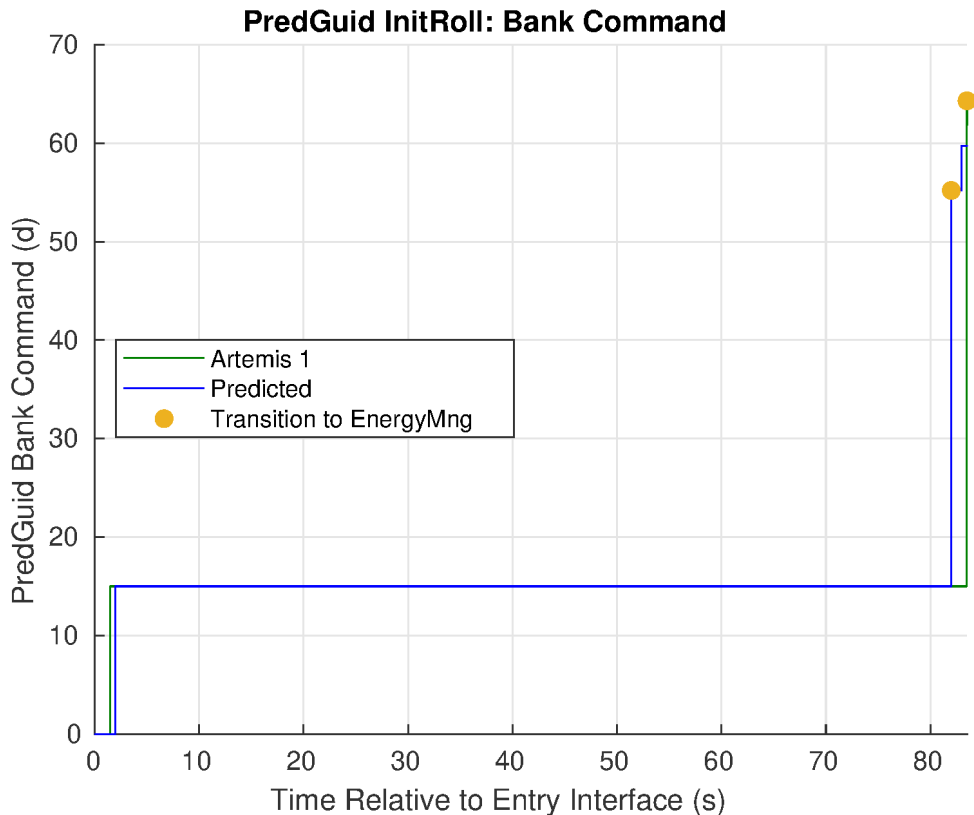




PREDGUID PHASE 1: INITIAL ROLL



- ◆ Holds pre-selected bank angle
- ◆ Includes skip out protection to command full lift-down if entry is too shallow
 - Skip out protection was not triggered during Artemis I
- ◆ Transitions to Energy Management phase when altitude rate goes above -700 ft/s

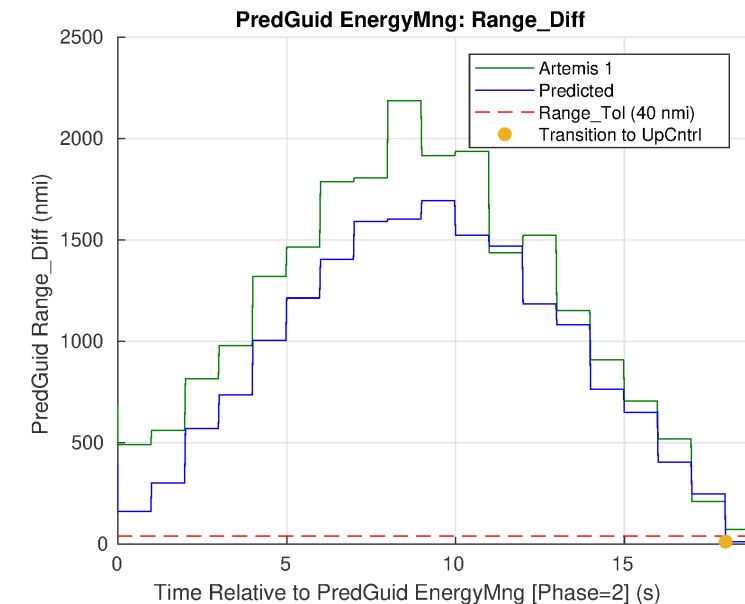
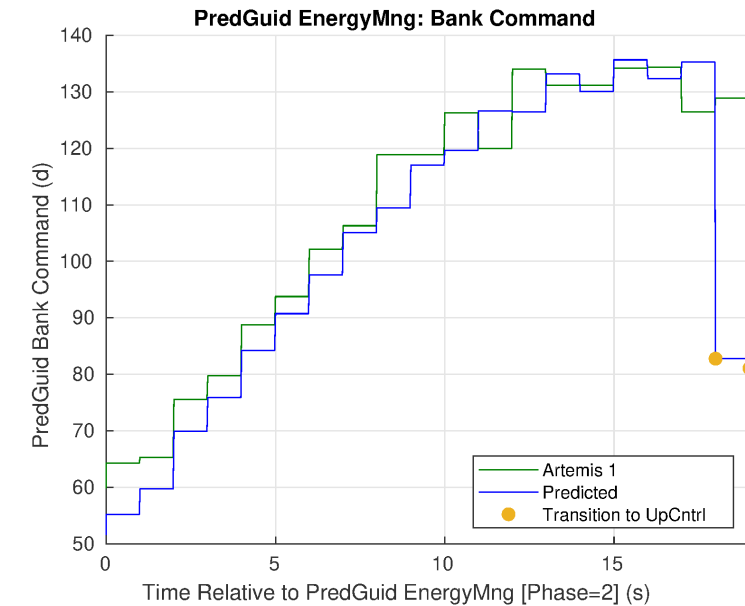




PREDGUID PHASE 2: ENERGY MANAGEMENT



- ◆ Retains original Apollo formulation of analytic predictor-corrector
- ◆ Two subphases
 - Hunttest
 - Analytically propagates a constant vertical L/D to find the range between current state and the initiation of the Final phase
 - Iterates on speed to converge on the range
 - Constant Drag
 - Selects the bank needed to bleed off energy to achieve the speed
- ◆ Transitions to Up Control when the range converges
- ◆ Differences between the predicted and actual trajectories are due to atmospheric and vehicle variations



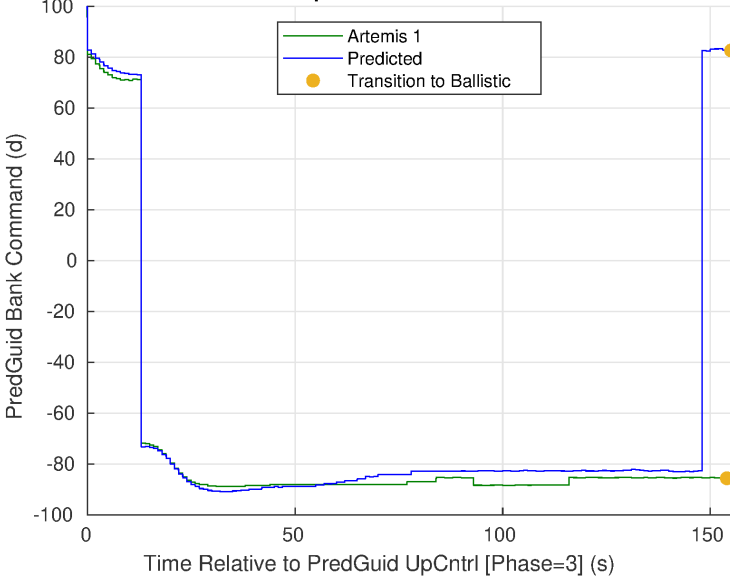


PREDGUID PHASE 3: UP CONTROL

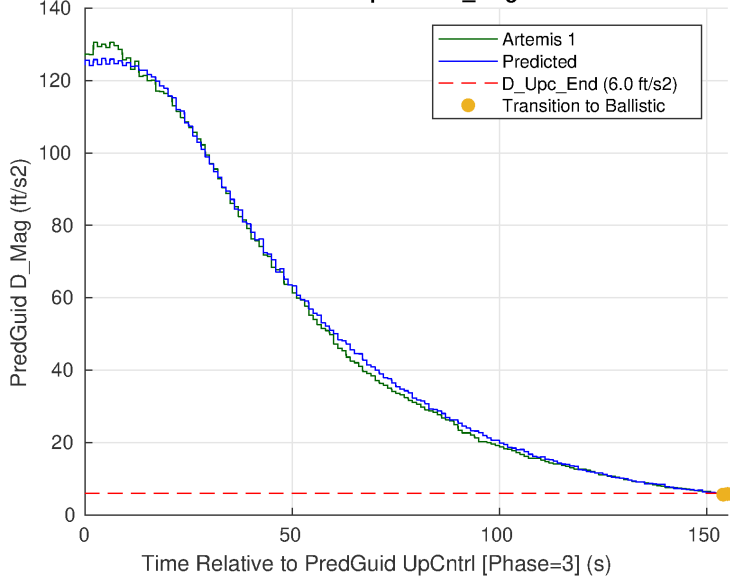


- ◆ Numerical Predictor Corrector
- ◆ Uses in-flight estimated density and L/D
- ◆ Transitions to Ballistic phase upon exit of sensible atmosphere

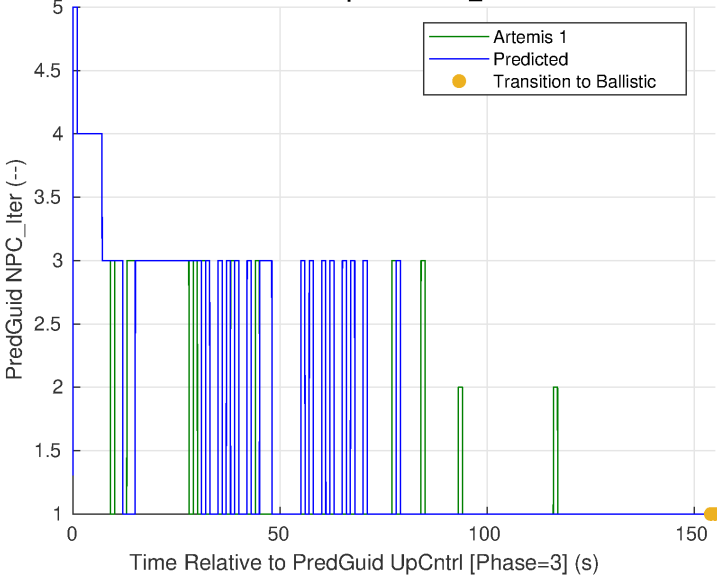
PredGuid UpCntrl: Bank Command



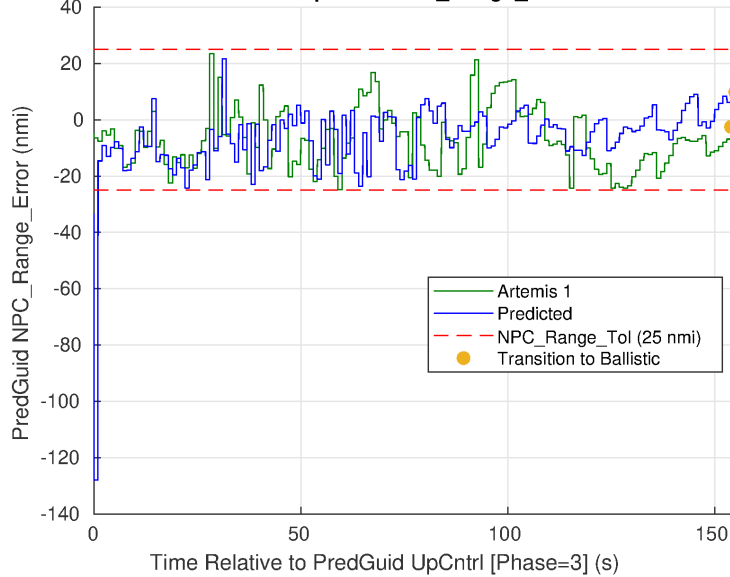
PredGuid UpCntrl: D_Mag



PredGuid UpCntrl: NPC_Iter



PredGuid UpCntrl: NPC_Range_Error

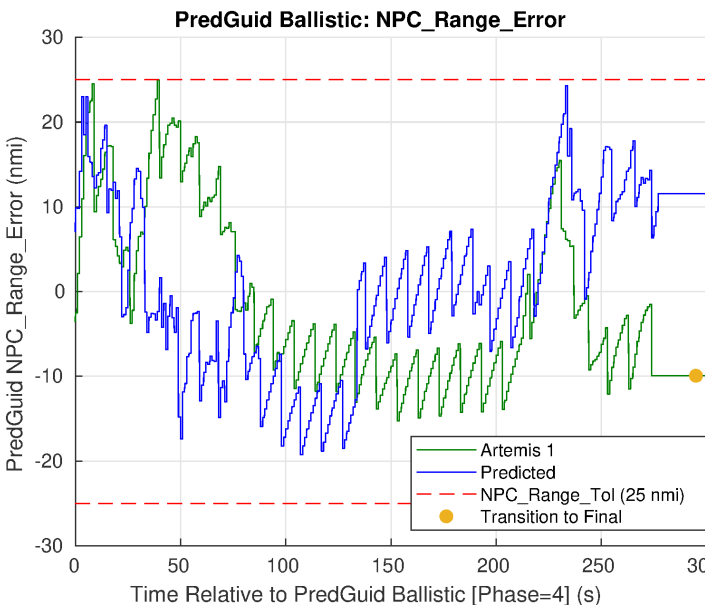
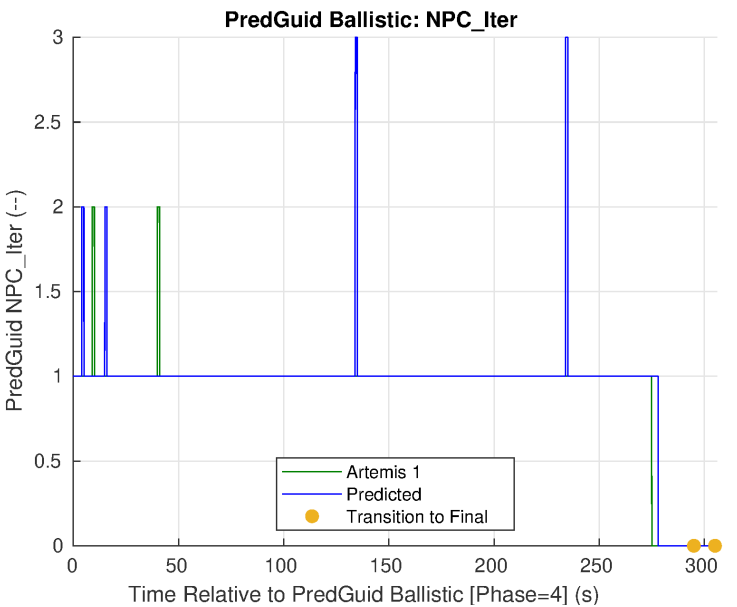
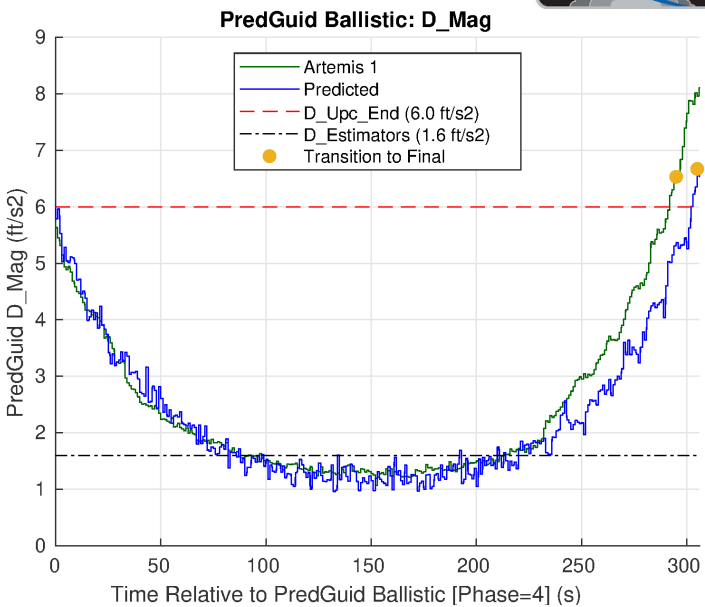
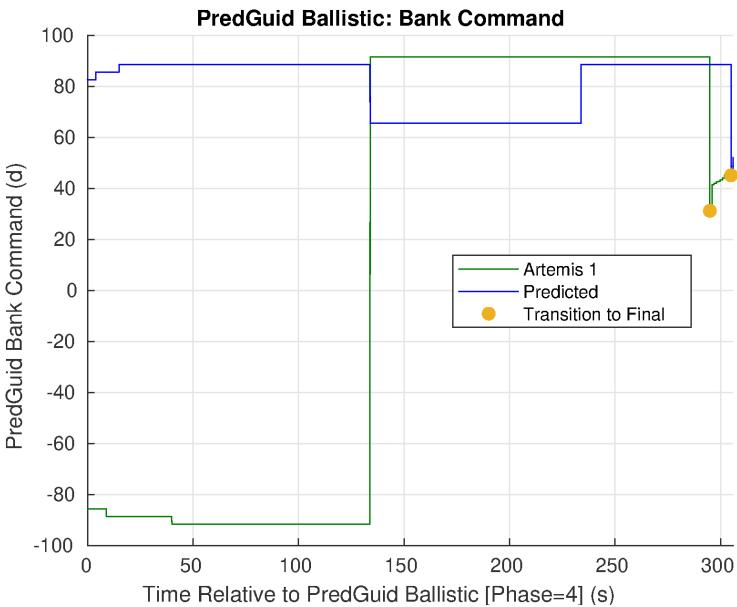




PREDGUID PHASE 4: BALLISTIC



- ◆ Low drag phase of flight
- ◆ Numerical Predictor Corrector
- ◆ Continues to update guidance command
- ◆ Uses in-flight estimated density and last estimated L/D before atmospheric exit

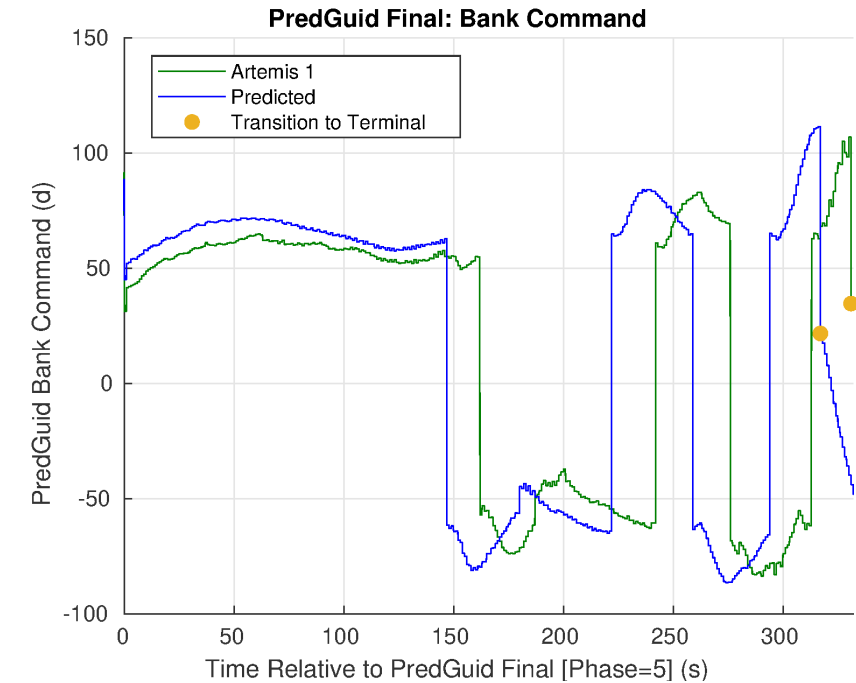




PREDGUID PHASE 5: FINAL



- ◆ **Uses Apollo formulation of Entry Terminal Point Controller**
 - Stored reference trajectory and gains
- ◆ **Includes g-limiter to alter bank angle in high g-load scenarios**
 - G-limiter was not triggered during Artemis I
- ◆ **Transitions to Terminal phase when speed drops below 1000 ft/s**





PREDGUID PHASE 6: TERMINAL

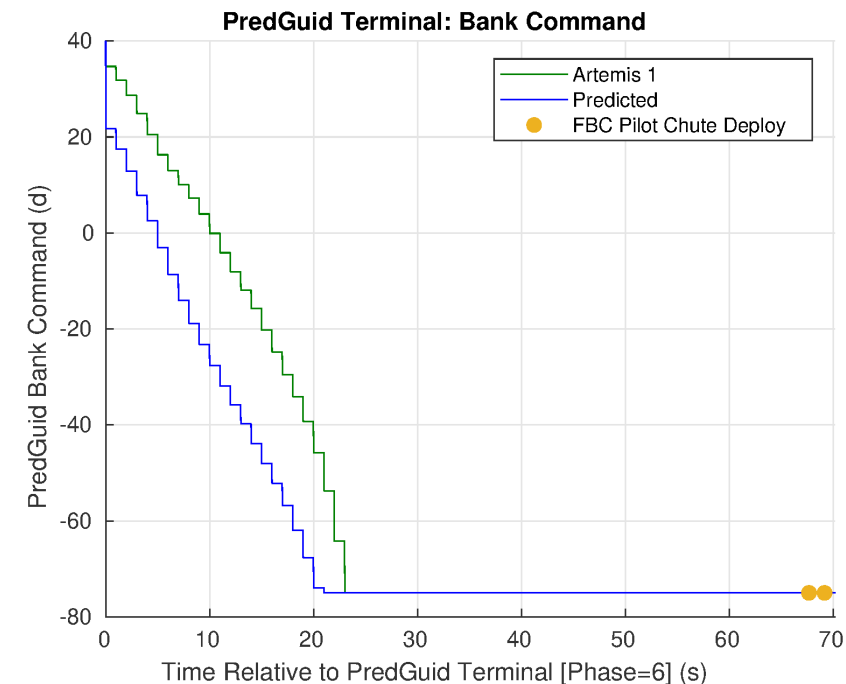


◆ Simple proportional guidance based on heading error

- Points at the target
- Holds command if vehicle flies past target

◆ Active guidance ends at beginning of chute sequence

- Forward Bay Cover (FBC) pilot chute deploy

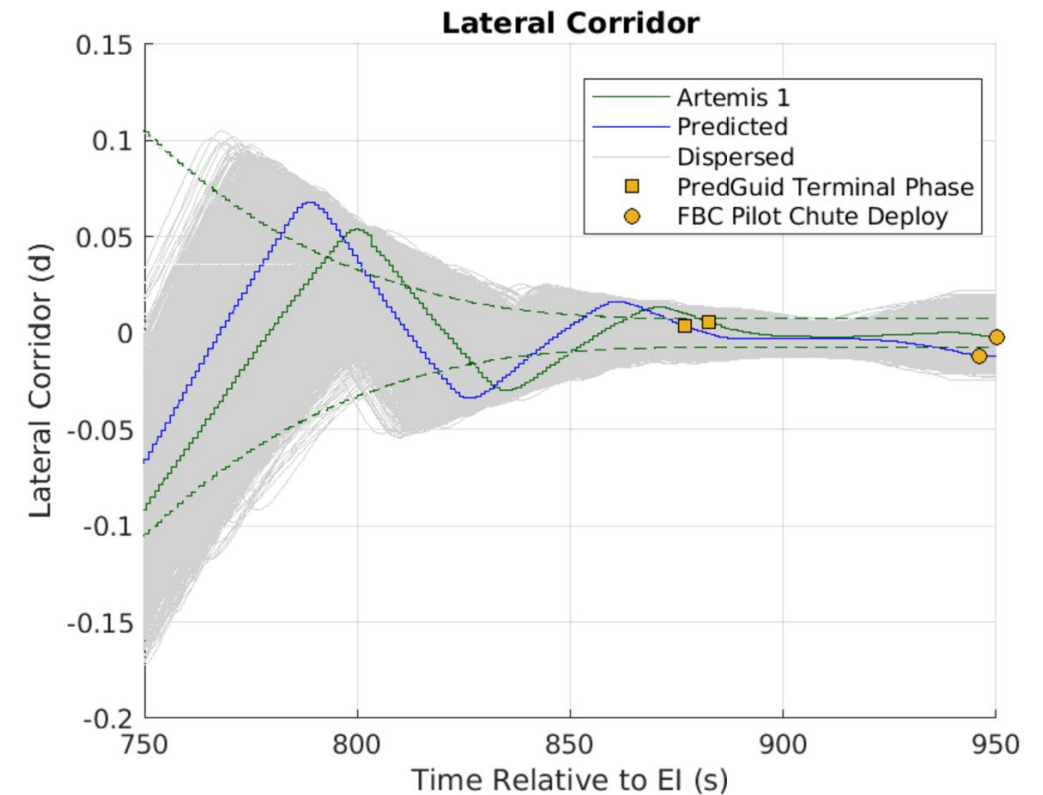
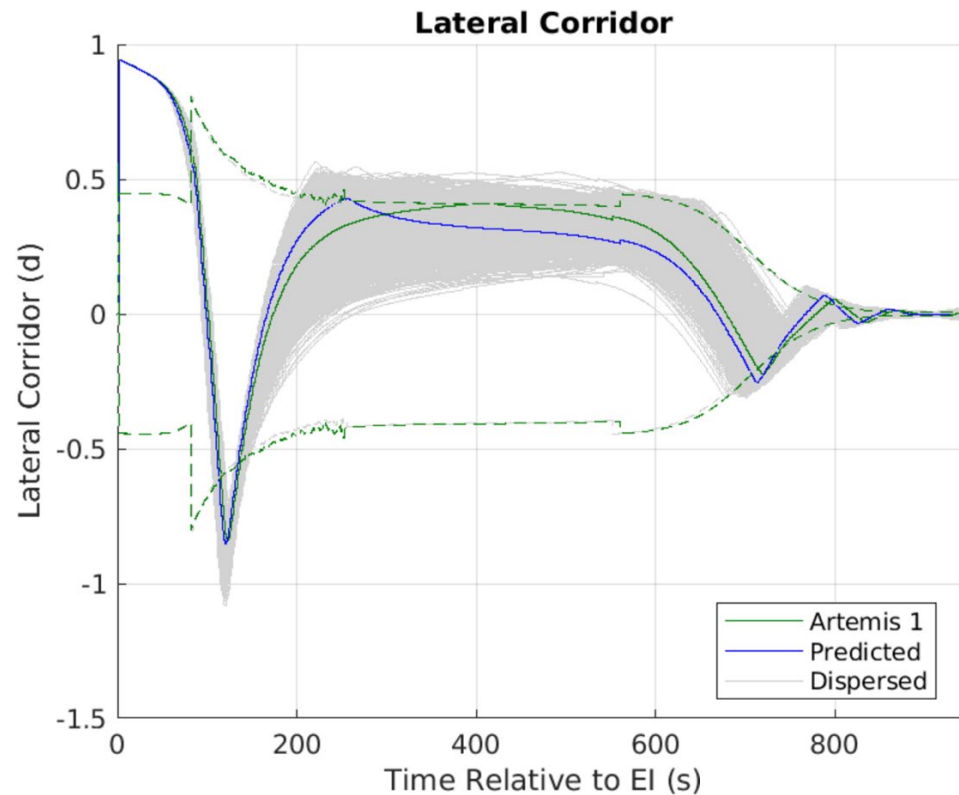




LATERAL CORRIDOR PERFORMANCE



- ◆ **Lateral channel controls crossrange using bank reversals**
 - Lateral deadband based on speed and L/D
- ◆ **Guidance commanded 6 bank reversals during flight**

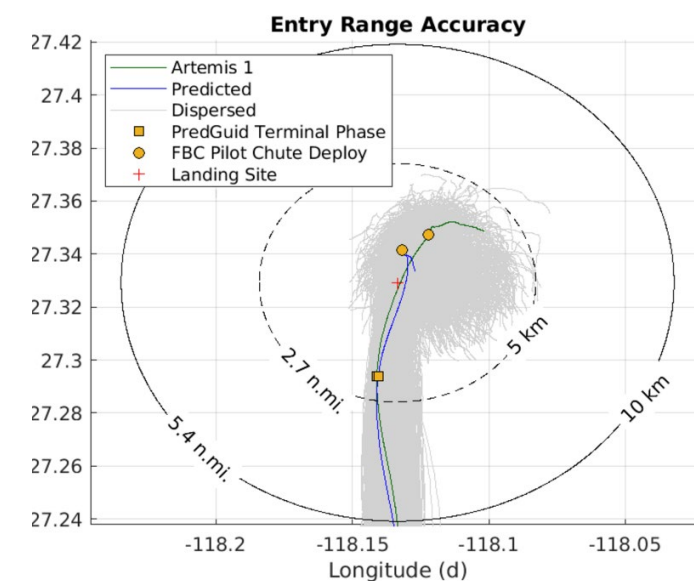
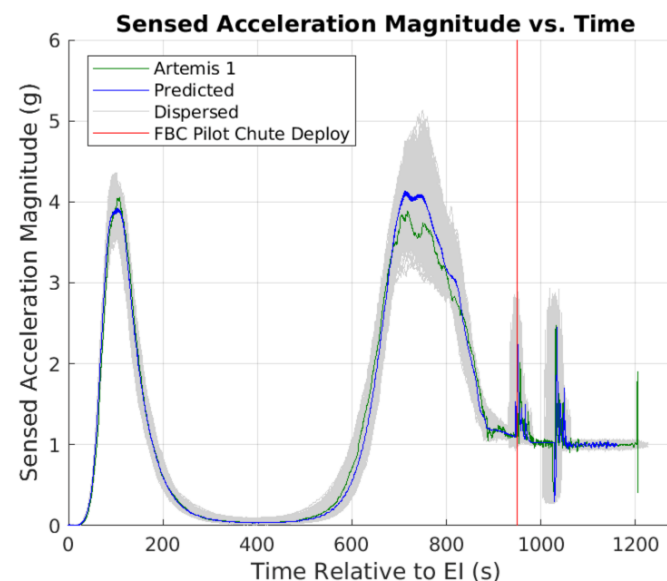
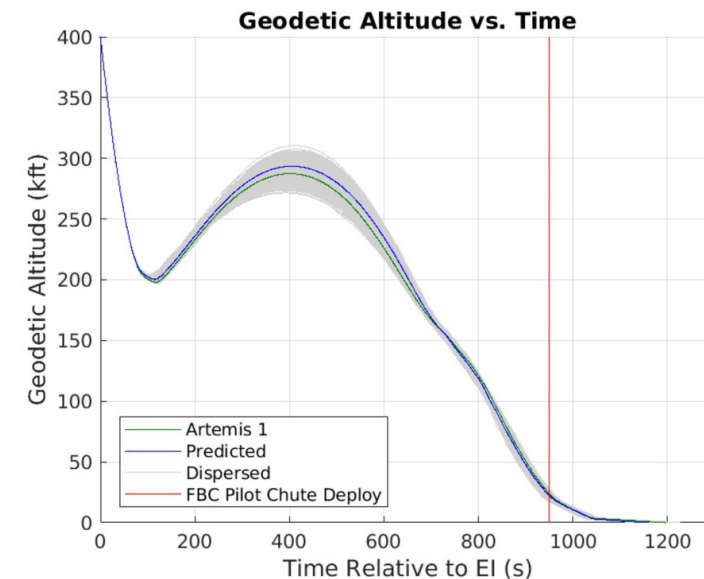
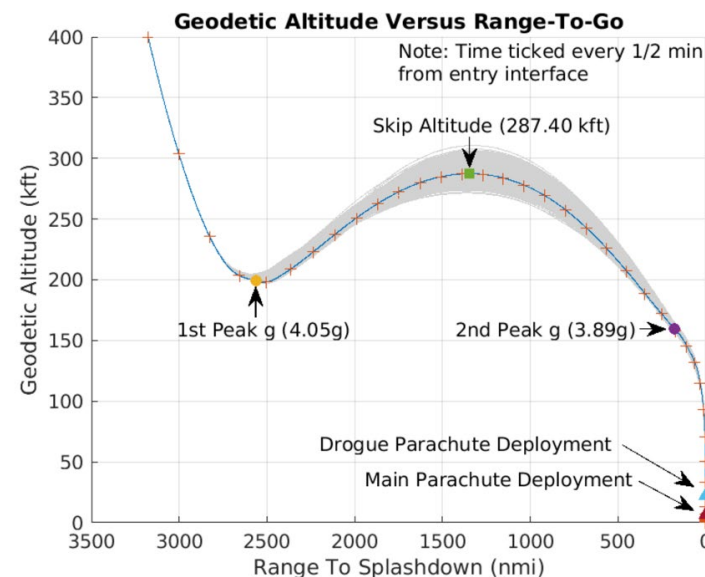




GUIDANCE RESULTS



- ◆ During Artemis I flight, the Orion entry guidance operated as expected and achieved the targeted landing site within the required accuracy
- ◆ The Artemis I flight did not skip as high as predicted
 - Predicted skip apogee: 293.5 kft
 - Actual skip apogee: 287.4 kft
 - Likely due to a less dense atmosphere during the first pass and slightly less lift-to-drag (L/D) than predicted.
- ◆ This data shows a successful skip entry

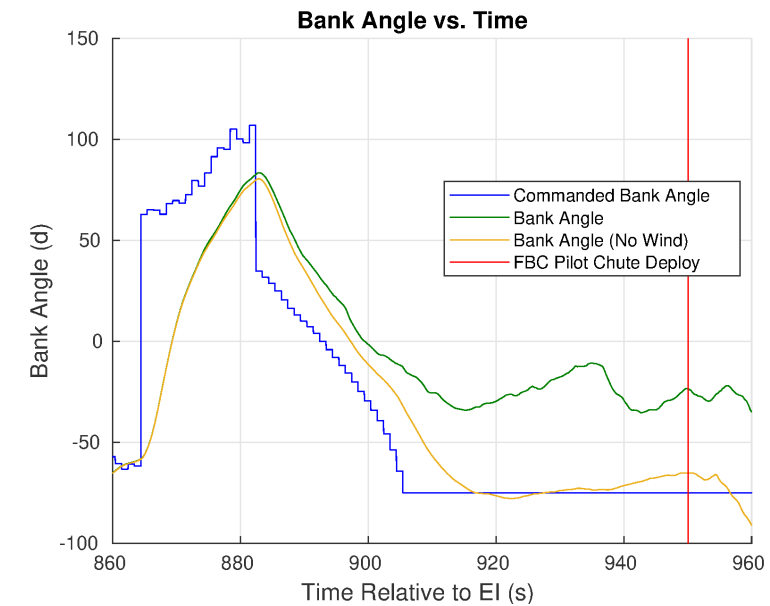
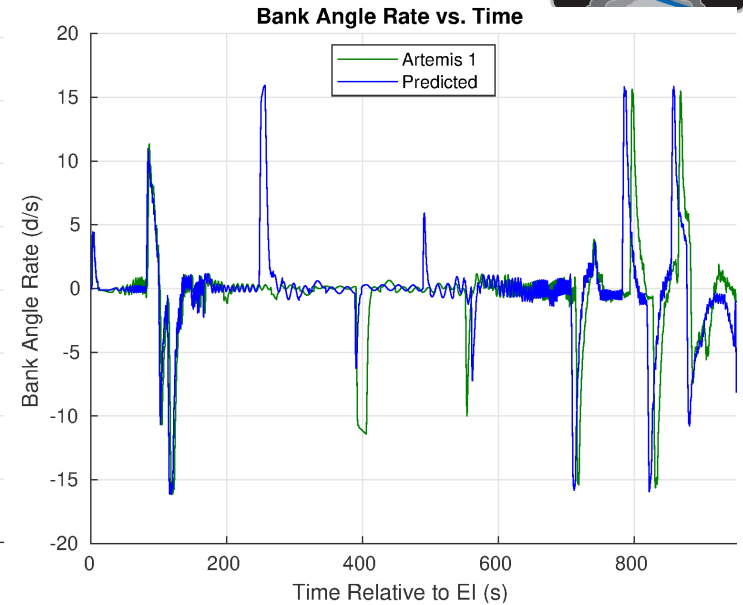
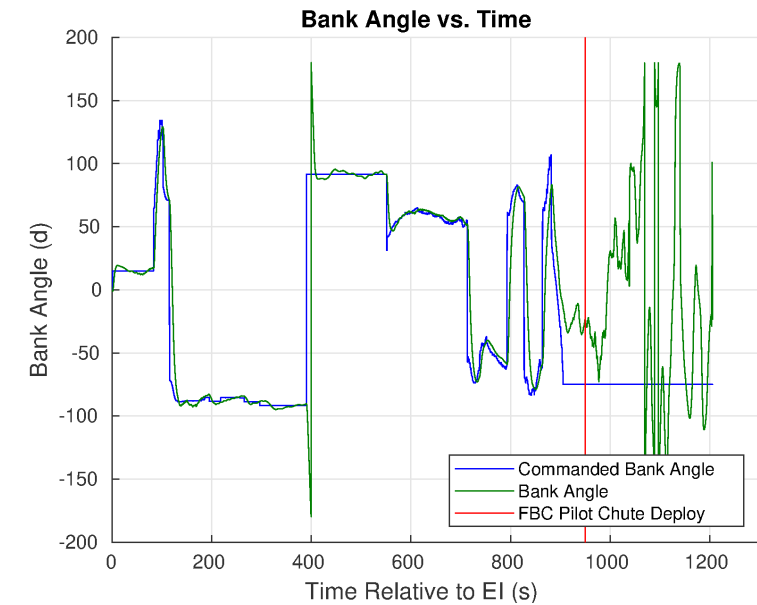




BANK ANGLE



- ◆ Navigated bank angle tracks commanded bank angle very well until the last 90 seconds of guided flight
- ◆ Navigated bank angle assumes no wind
 - As the vehicle slows down, the wind speed becomes significant relative to the speed of the vehicle
 - Assumption to ignore wind in the on-board computation of bank angle breaks down
- ◆ Contributing factor to the miss distance at chute deploy

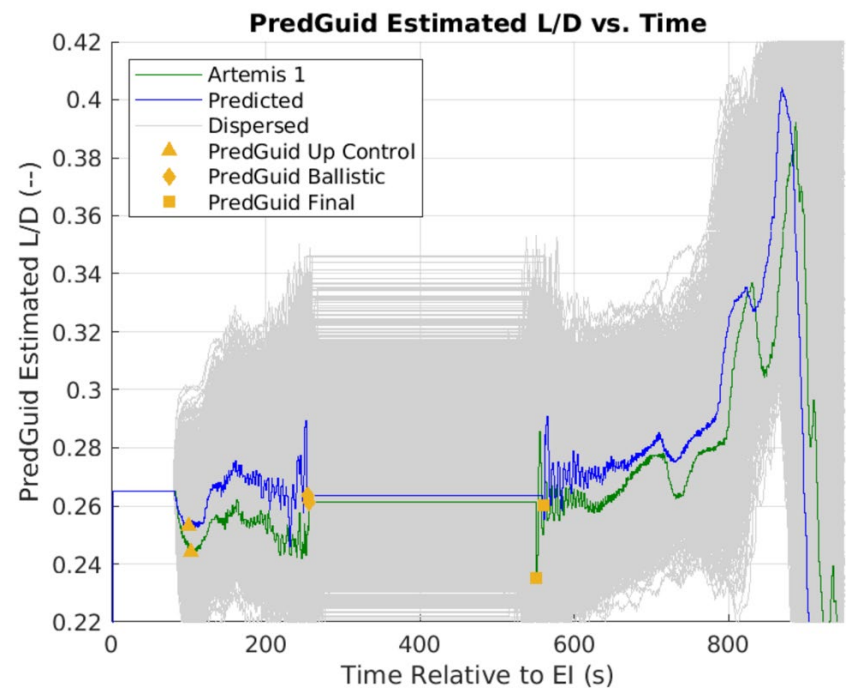
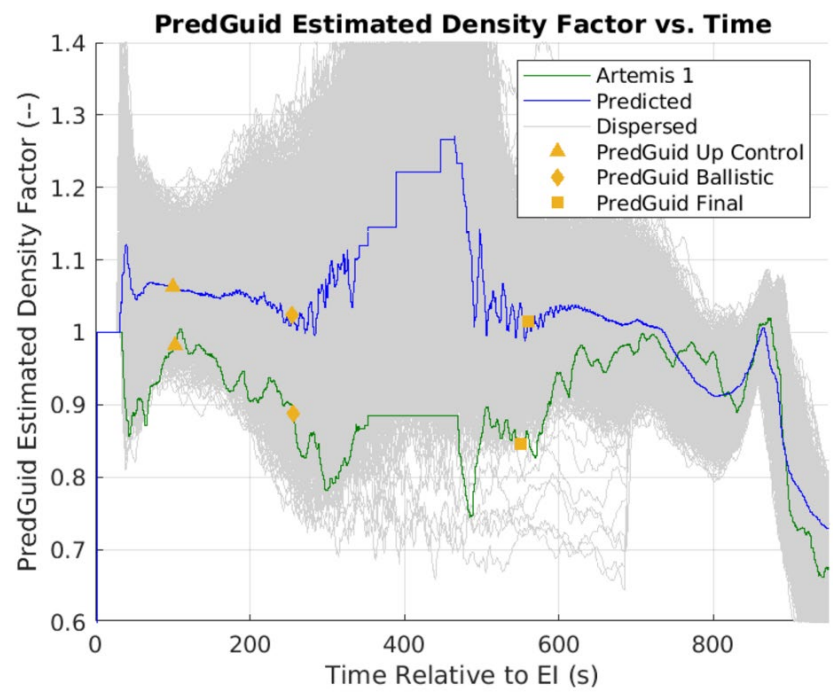




DENSITY AND L/D ESTIMATOR PERFORMANCE



- ◆ **Measured acceleration used to estimate:**
 - Density scale factor applied to on-board 1976 standard atmosphere
 - Lift-to-drag ratio
- ◆ **Artemis I flight experienced ~10% less dense atmosphere and ~5% less L/D than predicted**
 - Within expected dispersion envelope
 - Most likely cause of differences between predicted and actual flight

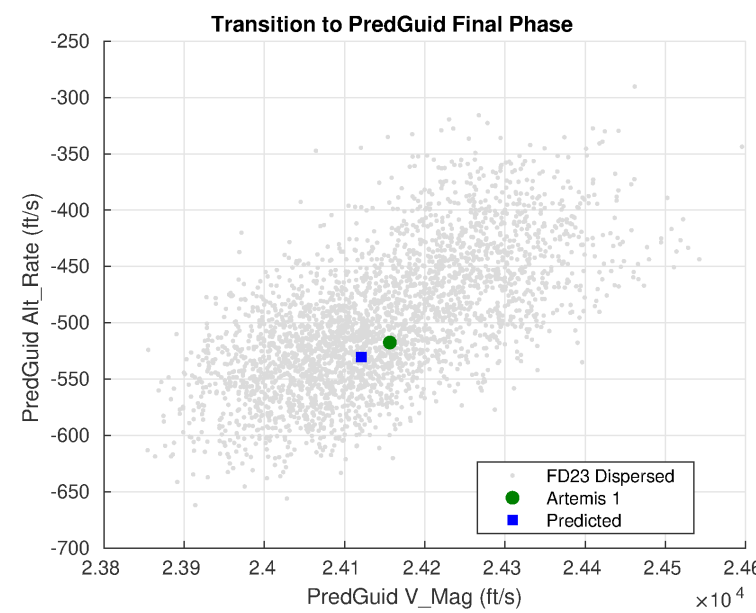
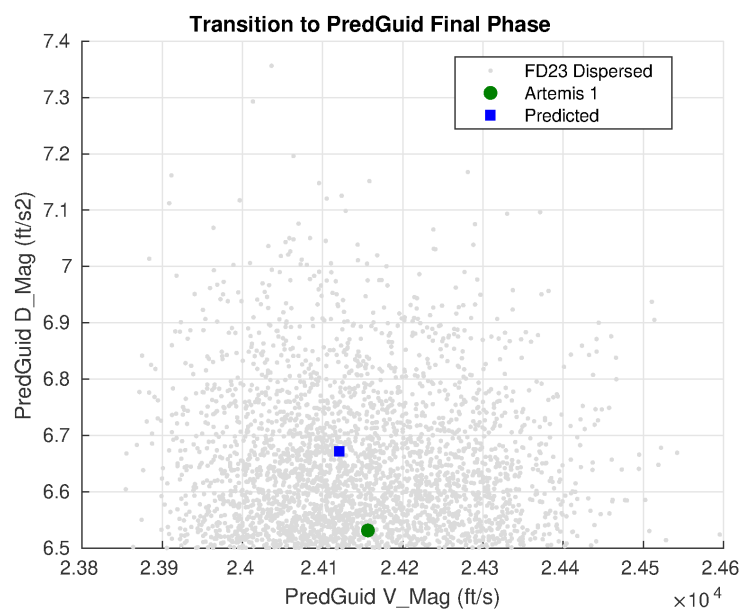
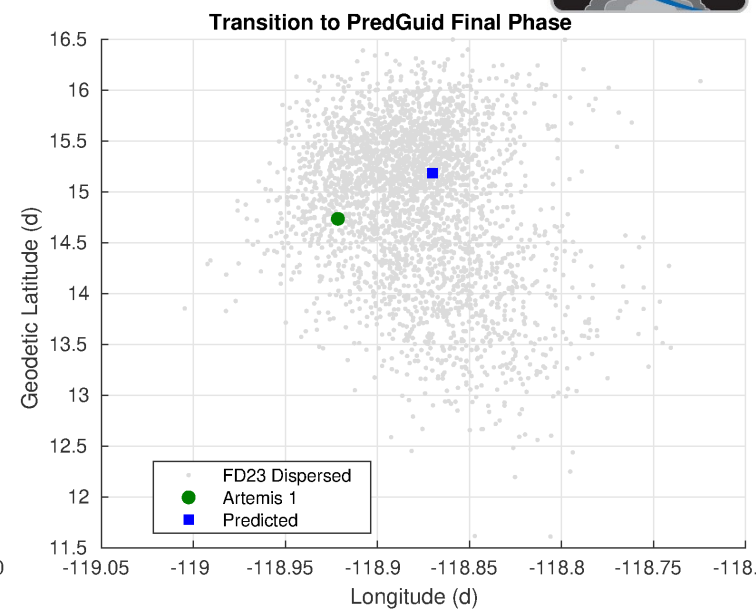
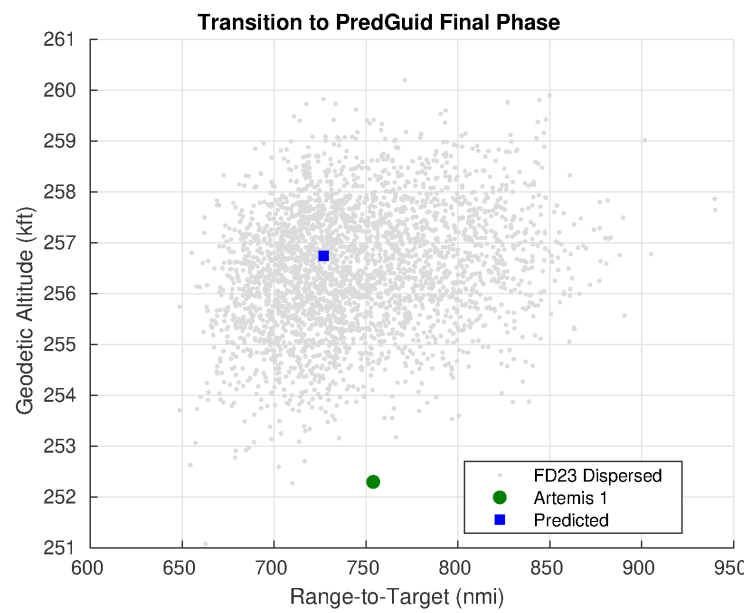




TRANSITION TO FINAL PHASE



- ◆ **Transition to Final phase is an important measure of the guidance performance**
 - Effectively at the second atmospheric entry since this is the point where the drag acceleration begins to increase
- ◆ **As noted, the Artemis I flight did not skip as high as predicted**
- ◆ **Geodetic altitude is not used during the Final phase and thus does not impact performance**

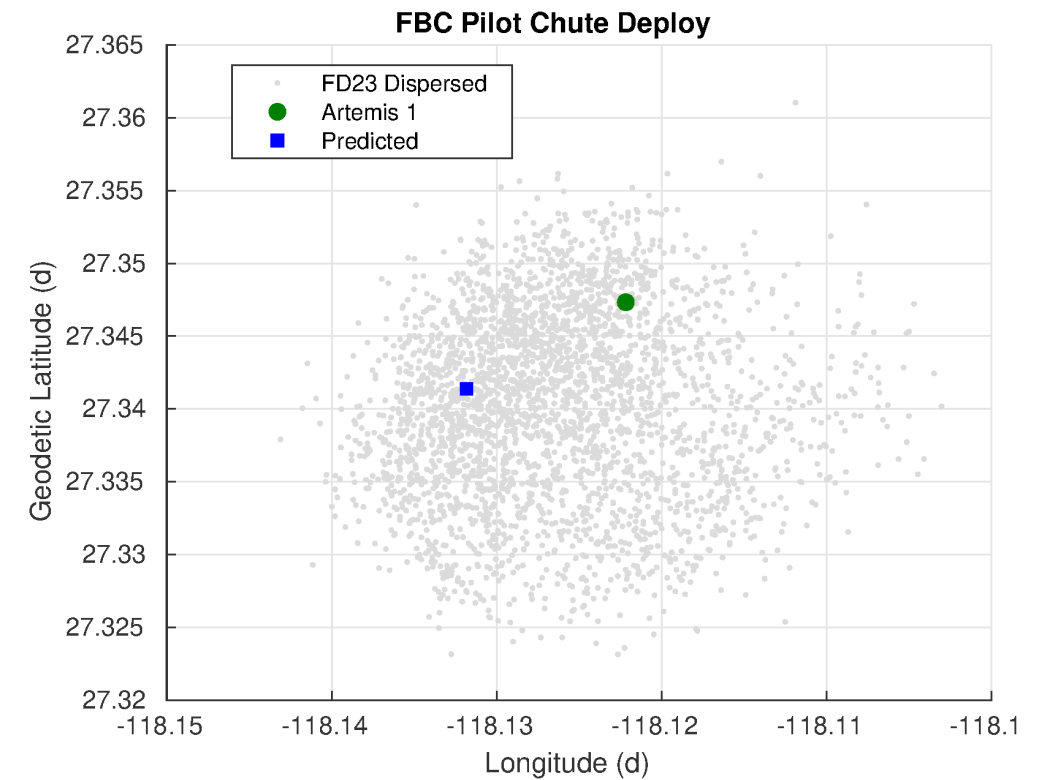
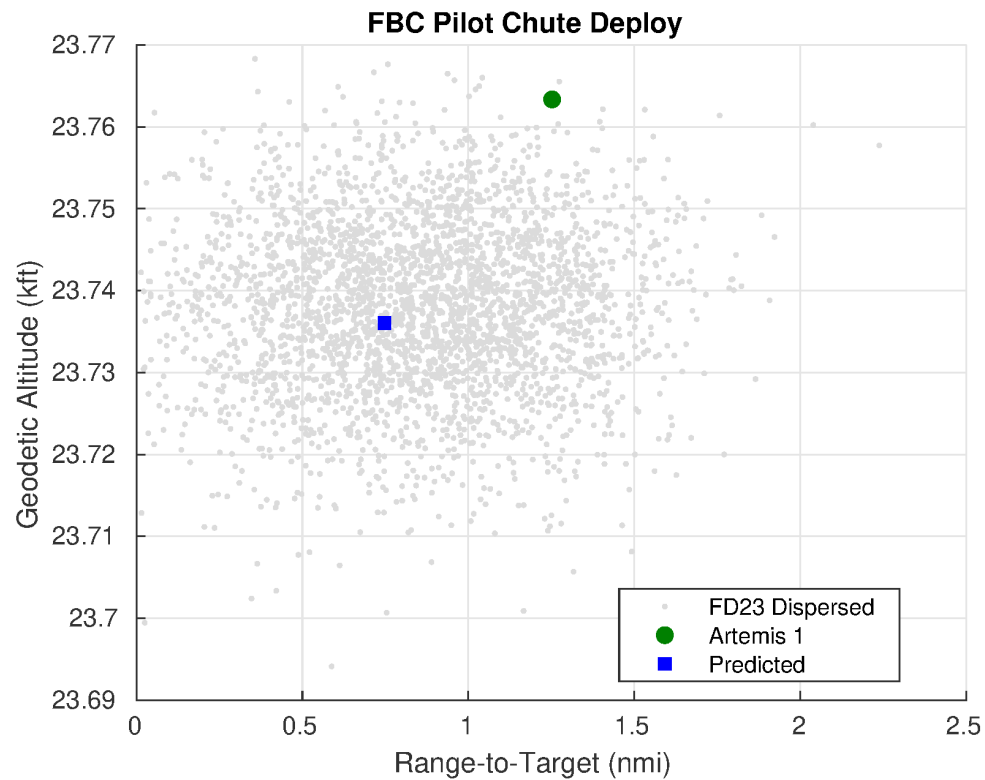




FORWARD BAY COVER PARACHUTE DEPLOY



◆ Forward Bay Cover (FBC) parachute deploy is the end of active entry guidance



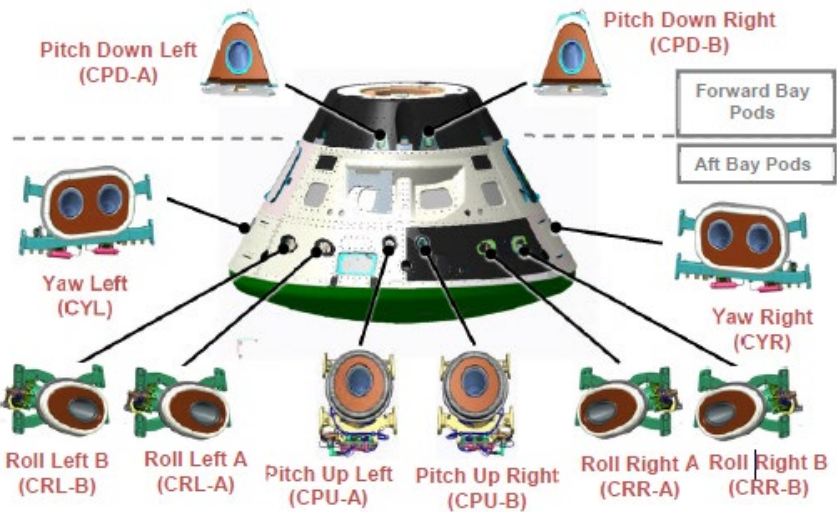


ENTRY CONTROL OVERVIEW



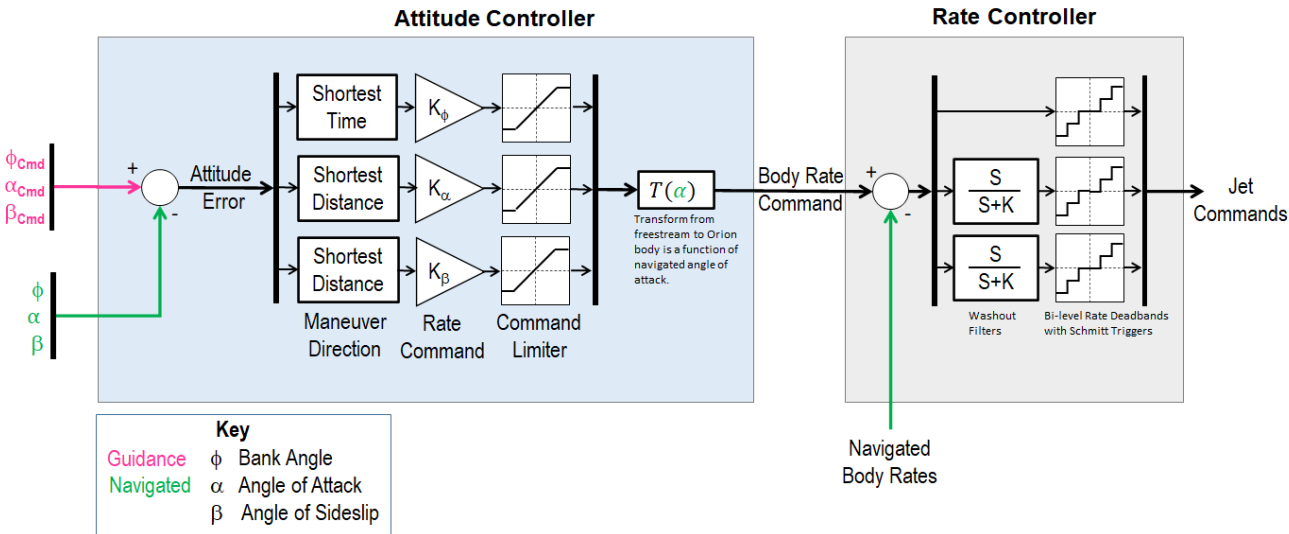
◆ Crew Module Reaction Control System (RCS)

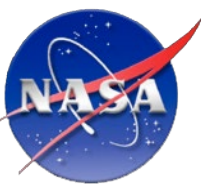
- Attitude control is achieved by commanding reaction control thrusters that produce torque about the vehicle body axis
 - Two fully redundant strings of thrusters
 - Six thrusters per string
 - Each thruster produces a nearly pure torque in one direction about the primary body axis



◆ Control Design

- The Crew Module control system (CNC) is a digital controller that operates at 40Hz
- 3-axis attitude control is performed during exo-atmospheric flight
 - Transition between exo-atmospheric and atmospheric gains is scheduled on acceleration magnitude
- Attitude maneuvering in atmosphere is limited to bank
 - Angle of sideslip and angle of attack are aero stabilized
- Atmospheric control gains are scheduled on velocity magnitude and are tailored for hypersonic, supersonic, transonic, and subsonic phases of flight

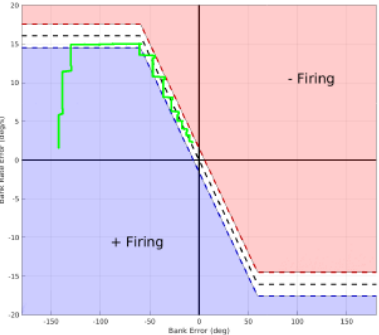




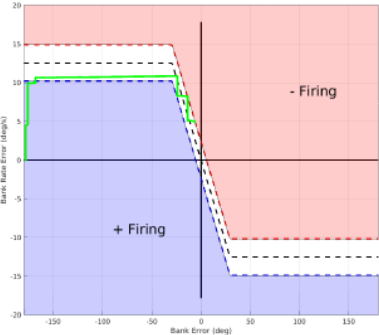
ENTRY CONTROL PERFORMANCE



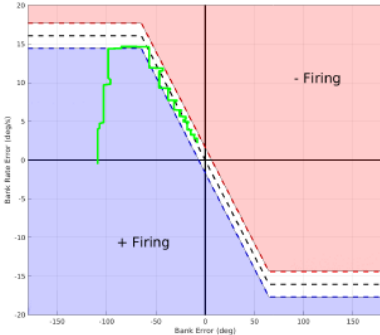
- ◆ Entry control tracked the bank angle command well during flight
- ◆ Attitude rates required little correction to stay within deadbands
 - Aero stability decreases during subsonic flight requiring more control corrections near the time of Forward Bay Cover (FBC) jettison
- ◆ Bank reversal maneuvers were well behaved and followed the control phase plane indicating CM RCS thrusters performed as expected



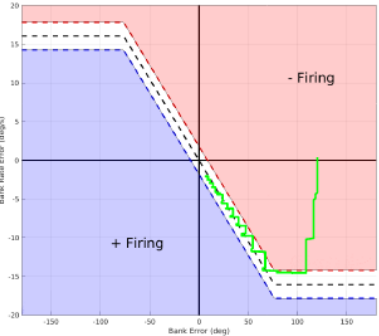
(a) Bank Reversal 1 Phase Plane



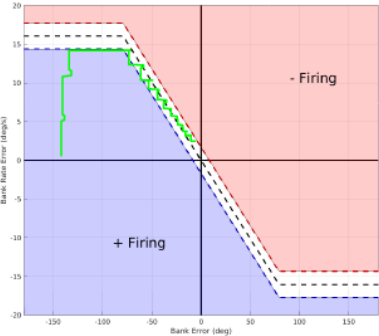
(b) Bank Reversal 2 Phase Plane



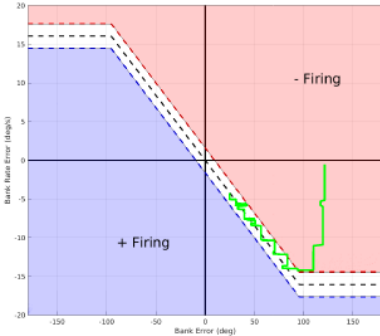
(c) Bank Reversal 3 Phase Plane



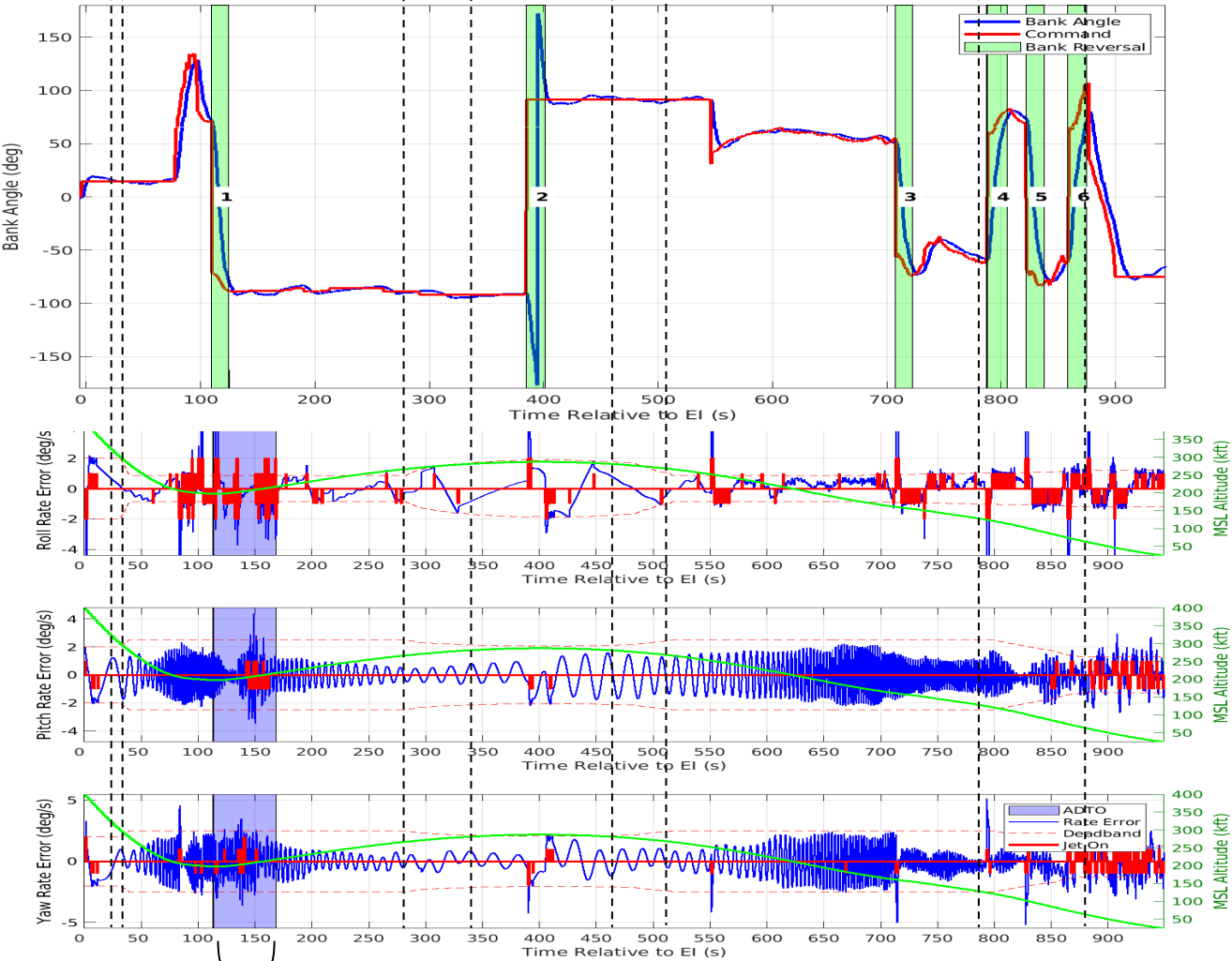
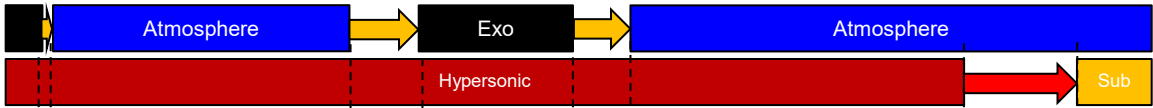
(d) Bank Reversal 4 Phase Plane



(e) Bank Reversal 5 Phase Plane



(f) Bank Reversal 6 Phase Plane



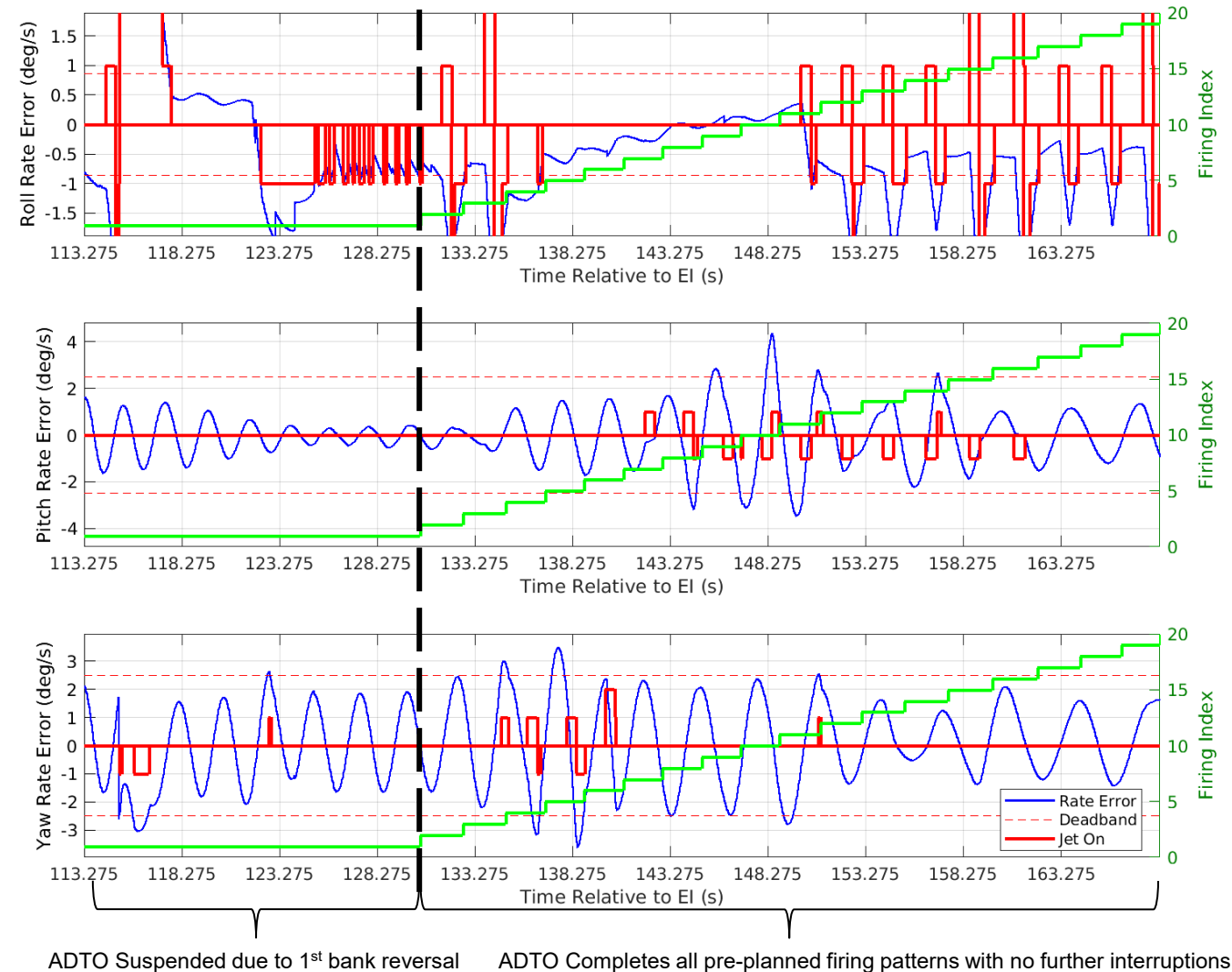


AEROTHERMAL DETAILED TEST OBJECTIVE



◆ Aerothermal Detailed Test Objective (ADTO)

- Series of RCS commands executed during hypersonic flight in the atmosphere
- Temperature sensors included on the CM back-shell measured the effect of RCS firings on heating for aerothermal model validation
- Unique to the Artemis I mission
- Open-loop firings
 - Prior to the firing a quiescent period is enforced
 - Post firing the control system corrects resulting disturbance
 - Firings are suspended by bank reversals or if significant attitude or rate disturbances are detected
 - The ADTO was suspended due to the 1st bank reversal
 - Attitude and attitude rate was well behaved during the ADTO. Minor excursions occurred due to ADTO firings but did not result in further suspension of the ADTO





CONCLUSION



◆ **Artemis I flight was within the predicted dispersed flight envelope**

- Differences between flight and best prediction due to 10% less dense atmosphere and 5% less L/D from predictions
- Even with these differences, the flight was close to the pre-flight predictions

◆ **Artemis I is the first successful demonstration of a skip entry for a human rated vehicle**

◆ **Acknowledgements**

- Original Apollo engineers
- Former team members Tim Crull, Mike Tigges, Gregg Barton, Zach Putnam, Andy Barth, and Travis Bailey